

**CONTROL IN ROBOTICS AND AUTOMATION: SENSOR
BASED INTEGRATION (ENGINEERING)**

Denisse N. Zimmerer

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In this section, the architecture of the platform is described. The increasing availability of artificial intelligence technologies, such as remote sensing, information and communication tools, big data, blockchain, Internet of Things and machine learning, can capture, elaborate and communicate historical and real-time data and provide opportunities for establishing cloud-based and collaborative logistic ecosystems. Wright, D.

Thebestcandidatepositionsarethentested,sensorsarecalibrated,andth Wright, M. The authors introduce visually guided control systems and study the role of computer vision in autonomously guiding a robot . Thesis,Carnegie-MellonUniversity,The model used to design the impedance controller, which includes the robot dynamic and the tool, is considered for the three Cartesian task-space axes.

